



01 - 02.7 03.23.GB

TWO-WAY AND THREE-WAY CONTROL VALVES LDM

RV 113







Control valves RV 113 R are flanged, 2-way valves with pressure balanced plug (except DN 15-25) and high tightness designed for regulation and closing of the medium flow.

Its design enables the valve to be applicable at high differential pressures with low-linear-force actuators. Owing to unique flow characteristic LDMspline*, optimized for regulation of thermodynamic processes, the valves are ideal for applications in heating and air-conditioning. Flow characteristics, Kvs values and leakage rates correspond to international standards.

The valves type RV 113 R have connection to the following actuators: Siemens, Belimo, Ekorex, LDM a PS Automation.

Application

Control valves RV113 are designed for applications in heating and air-conditioning. Control valves type RV113 are also available in silicone free execution (marking in a specification number SF). The maximum permissible operating pressures are specified below on this page.

Process media

The valves RV113 are suitable for media such as water, air and other media compatible with material of body and internal parts in range ± 2 to ± 150 °C.

Sealing surfaces of trim are resistant to common dirt and impurities in medium. However, for abrasive impurities it is recommended to pipe a strainer before the valve to ensure reliable function.

The valve cannot work in cavitation conditions.

Installation

The valve must be piped with the medium flow according to arrows indicated on the valve body.

The valve can be piped in any position except when the actuator is under the valve body.

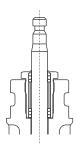
Flow characteristic selection in regard of valve stroke

To make right selection of valve flow characteristic, it is suitable to carry out checking of what stroke values will be reached in different operation states. We recommend to carry out such checking at least for minimal, nominal and maximal flow rates. The principle for flow characteristic selection is to avoid, if possible, 5,10% of the beginning and end of the valve stroke range.

To calculate valve stroke at different operating conditions with different types of flow characteristics is possible with the advantage of using LDM's calculation programme VALVES. The programme serves for complete design of valve from Kv calculation to specification of a concrete valve with its actuator.

Packing O-ring EPDM

Well proven type of packing with sealing elements made of high quality EPDM is suitable for operating with temperature of, \pm 2 to \pm 150 C. The packing excels with its reliability and long time tightness. Its properties ensure safe usage in nomaintanance applications. Main preferences of the packing is low frictional forces, sealing capability in both ports (even when there is underpressure in the valve) and service life exceeding 500 000 cycles.







RV 113 R

Two-way control valves

DN 15 - 40, PN 6 DN 15 - 150, PN 16 DN 15 - 150, PN 25

PV 11	13 P						
DN 15 t							
DN 15 - 40, PN 6; DN 15 - 150, PN 16	DN 15 - 150, PN 25						
Grey cast iron EN-JL 1040	Spheroidal cast iron EN-JS 1025						
Stainless steel 1	1.4027 (1.4028)						
Stainless steel 1.4305							
EPDM							
EPC	DM						
+2 to +3	150 °C						
Flanges type B1							
	* * * * * * * * * * * * * * * * * * * *						
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	, , , , , , , , , , , , , , , , , , , ,						
	DN 15 - 40, PN 6; DN 15 - 150, PN 16 Grey cast iron EN-JL 1040 Stainless steel 1 Stainless st EPE EPE +2 to +						

Maximum permissible operating pressures [MPa] dle ČSN EN 1092-2											
Material	PN	Tempera 120	ture [°C] 150								
Grey cast iron EN-JL 1040	6	0,60	0,54								
(EN-GJL-250)	16	1,60	1,44								
Spheroidal cast iron EN-JS 1025 (EN-GJS-400-18-LT)	25	2,50	2,43								



Kvs values and differential pressures

The value $\Delta p_{\text{\tiny max}}$ is maximum differential pressure when reliable closing and opening is guaranteed. Because of the seat and plug service life, it is recommended so that permanent differential pressure would not exceed 0.4 MPa.

For furth	er info	Actua	ating (a	actuat	or)		see the to	able on nex	t page					
on actua	0	Linea	r force	•			800 N	1000 N	1500 N	2000 N	2500 N	3200 N	4000 N	4500 N
catalogu			Κι	/s [m³/	h]		Δp_{max}							
DN	Н	1	1 2 3 4 5				MPa							
15		4	2.5	1.6	1	0.63	2.28	2.50	2.50	2.50	2.50			
20		6.3	4.0	2.5			1.43	1.96	2.50	2.50	2.50			
25		10	6.3	4.0			0.91	1.25	2.11	2.50	2.50			
32	20	16	10	6.3			2.50	2.50	2.50	2.50	2.50			
40	20	25	16	10			2.50	2.50	2.50	2.50	2.50			
50		40	25	16			2.50	2.50	2.50	2.50	2.50	2.50	2.50	2.50
65		63	40	25			2.50	2.50	2.50	2.50	2.50	2.50	2.50	2.50
80		100	63	40			2.50	2.50	2.50	2.50	2.50	2.50	2.50	2.50
100		160	100	63						2.50	2.50	2.50	2.50	2.50
125	40	250	160	100						2.50	2.50	2.50	2.50	2.50
150		360	250	160						2.50	2.50	2.50	2.50	2.50

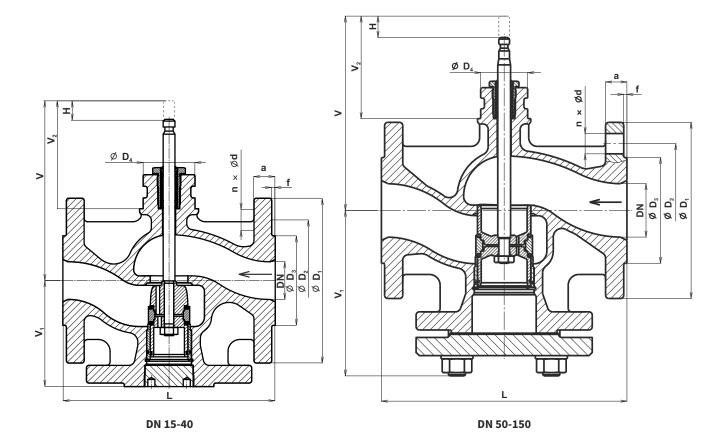


			stroke	
Siemens	Electric actuator SAX 31.00 a SAX 31.03	AC 230 V, 3-position control, 800 N		
	Electric actuator SAX 81.00 a SAX 81.03	AC/DC 24 V, 3-position control, 800 N	20 mm	
	Electric actuator SAX 61.03	AC/DC 24 V, control 010V, 420mA, 0-1000Ω, 800 N		
Belimo	Electric actuator NV230A-RE	AC 230 V, 3-position control, 1000 N		
	Electric actuator NV24A-RE	AC/DC 24 V, 3-position control, 1000 N		
	Electric actuator NV24A-MP-RE	AC/DC 24 V, DC (0) 210V, 1000 N		
	Electric actuator NVC24A-MP-RE	AC/DC 24 V, DC (0) 210V, 1000 N		
	Electric actuator NVK24A-3-RE	AC/DC 24 V, 3-position control, 1000 N		
	Electric actuator NVK24A-MP-RE	AC/DC 24 V, DC (0) 210V, 1000 N		
	Electric actuator NVK230A-3-RE	AC 230 V, 3-position control, 1000 N	20 mm	
	Electric actuator NVKC24A-MP-RE	AC/DC 24 V, DC (0) 210V, 1000 N		
	Electric actuator SV24A-MP-RE	AC/DC 24 V, DC (0) 210V, 1500 N		
	Electric actuator SV230A-RE	AC 230 V, 3-position control, 1500 N		
	Electric actuator SV24A-RE	AC/DC 24 V, 3-position control, 1500 N		
	Electric actuator SVC24A-MP-RE	AC/DC 24 V, DC (0) 210V, 1500 N		
	Electric actuator EV230A-RE	AC 230 V, 3-position control, 2500 N		
	Flectric actuator EV24A-RE	AC/DC 24 V, 3-position control, 2500 N		
	Electric actuator EV24A-MP-RE	AC/DC 24 V, DC (0) 210V, 2500 N		
	Electric actuator EVC24A-MF-RE	AC/DC 24 V, DC (0) 210V, 2500 N	40 mm	
	Electric actuator EV24A-MF-RE	AC/DC 24 V, DC (0) 210V, 2500 N		
Ekorex	Flectric actuator PTN2-XX.0	AC 230 V, 3-position control, 010V, 420mA,		
EROIEX		2000 - 4000 N	20 - 40 mm	
E	Electric actuator PTN2-XX.2	AC 24 V, 3-position control, 010V, 420mA 2000 - 4000 N	25 16 11111	
-DM	Electric actuator ANT40.11	AC/DC 24 V (230 V with modul), 2500 N		
		3(2)-position control, 010V, 420mA		
	Electric actuator ANT40.11S	AC/DC 24 V (230 V s modulem), 2000 N		
		3(2)-position control, 010V, 420mA	20 - 40 mm	
		fail-safe function - indirect		
	Elektrický pohon ANT40.11R	AC/DC 24 V (230 V s modulem), 2000 N		
		3(2)-position control, 010V, 420mA		
		fail-safe function - direct		
PS	Electric actuator PSL202 AMS11	AC 230 V, AC/DC 24 V, 2300 N		
Automation		3-position control, 0(2)-10 V; 0(4)-20 mA	20 - 40 mm	
	Electric actuator PSL204 AMS11	AC 230 V, AC/DC 24 V, 4500 N		
		3-position control, 0(2)-10 V; 0(4)-20 mA	40	
	Electric actuator PSL204 AMS12	AC 230 V, AC/DC 24 V, 4500 N	40 mm	
		3-position control, 0(2)-10 V; 0(4)-20 mA		
	Electric actuator PSF401	AC 230 V, AC/DC 24 V, 1000 N	22	
	(mechanical fail-safe function)	3-position control, 0(2)-10 V; 0(4)-20 mA	20 mm	
	Electric actuator PSF402	AC 230 V, AC/DC 24 V, 2000 N		
	(mechanical fail-safe function)	3-position control, 0(2)-10 V; 0(4)-20 mA		
	Electric actuator PSF402.1	AC 230 V, AC/DC 24 V, 2000 N	20 - 40 mm	
	(mechanical fail-safe function)	3-position control, 0(2)-10 V; 0(4)-20 mA		
	Electric actuator PSF-M402	AC 230 V, AC/DC 24 V, 2000 N		
		3-position control, 0(2)-10 V; 0(4)-20 mA		



Dime	ensior	ns and	l weig	hts fo	r the	type	RV 11	3 R							
				PN 6				PN 16							
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₁	D ₂	D ₃	d	n	а	m	
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	
15	80	55	38	11	4	12	2.6	95	65	46	14	4	14	3.5	
20	90	65	48	11	4	14	3.5	105	75	56	14	4	16	4.6	
25	100	75	58	11	4	14	4.1	115	85	65	14	4	16	5.4	
32	120	90	69	14	4	16	6.3	140	100	76	19	4	18	8.5	
40	130	100	78	14	4	16	7.9	150	110	84	19	4	18	10.5	
50								165	125	99	19	4	20	16.7	
65								185	145	118	19	4	20	23.0	
80								200	160	132	19	8	22	29.5	
100								220	180	156	19	8	24	40.5	
125								250	210	184	19	8	26	58.8	
150								285	240	211	23	8	26	80.7	

				PN 25						PN 6, I	PN 16, P	N 25		
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₄	f	L	V	V ₁	V ₂	н
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
15	95	65	46	14	4	14	3.5	44	2	130	167	65	96	20
20	105	75	56	14	4	16	4.6	44	2	150	167	75	96	20
25	115	85	65	14	4	16	5.4	44	3	160	167	80	96	20
32	140	100	76	19	4	18	8.5	44	3	180	177	90	96	20
40	150	110	84	19	4	19	10.5	44	3	200	187	100	96	20
50	165	125	99	19	4	19	16.7	44	3	230	182	155	96	20
65	185	145	118	19	8	19	23.0	44	3	290	192	185	96	20
80	200	160	132	19	8	19	29.5	44	3	310	212	193	96	20
100	235	190	156	23	8	19	39.8	44	3	350	247	216	116	40
125	270	220	184	28	8	19	56.4	44	3	400	272	239	116	40
150	300	250	211	28	8	20	78.1	44	3	480	297	284	116	40







RV 113 M

Three-way control valves

DN 15 - 40, PN 6 DN 15 - 150, PN 16 DN 15 - 150, PN 25

Technical data									
Series	RV 1	13 M							
Type of valve	Three-way c	ontrol valve							
Nominal size range	DN 15	to 150							
Nominal pressure	DN 15 - 40, PN 6; DN 15 - 150, PN 16	DN 15 - 150, PN 25							
Body material	Grey cast iron EN-JL 1040	Spheroidal cast iron EN-JS 1025							
Plug material	Stainless steel 1.4	027 (1.4028)							
Stem material	Stainless stee	el 1.4305							
Seat sealing	EPI	DM							
Packing	EPDM								
Operating temperature range	+2 to +	150 °C							
Connection	Flanges type Bi								
	Acc. to ČSN-EN	. , , ,							
Face to face dimensions	Section 1 acc. to ČS	SN-EN 558 (9/2008)							
Type of plug	Flanges type B1 (raised-fa	aced), linear in angle way							
Flow characteristic	LDMs	pline®							
Kvs values	0,63 to 3	60 m ³ /h							
Leakage rate	Class IV S1 acc. to ČSN-EN 1	.349 (5/2001) (<0.0005 % Kvs)							
Leakage rate in angle way	not guarante	ed (<2% Kvs)							
Rangeability r 50:1									

pressures [MPa] acc. to \dot{c}	SN	EN 10	92-2		
Material	PN	Temperatures [°C]			
Materiat	PIN	120	150		
Grey cast iron EN-JL 1040	6	0,60	0,54		
(EN-GJL-250)	16	1,60	1,44		
Spheroidal EN-JS 1025	25	2,50	2,43		
(EN-GJS-400-18-LT)	23	2,50	2,43		

Maximum permissible operating



Kvs values and differential pressures

The value Δp_{max} is maximum differential pressure when reliable closing and opening is guaranteed. Because of the seat and plug service life, it is recommended so that permanent differential pressure would not exceed 0.4 MPa (Grey cast iron) respective 0.6 Mpa (Spheroidal cast iron).

For furth	ner info.	Actua	ating (actuat	or)		see the	table on n	ext page						
on actua	ating see rs'	Linea	r force	•			800 N	1000 N	1500 N	2000 N	2300 N	2500 N	3200 N	4000 N	4500 N
	ue sheets		1/-	Г 3 /	U-1		۸۵	۸۵	۸۵	۸۵	۸۵	۸۵	۸۵	٨٥	٨٥
			K	/s [m³/	nj		Δp_{max}								
DN	H	1	2	3	4	5	MPa								
15		4	2.5	1.6	1	0.63	2.28	2.50	2.50	2.50	2.50	2.50			
20		6.3	4.0	2.5			1.43	1.96	2.50	2.50	2.50	2.50			
25		10	6.3	4.0			0.91	1.25	2.11	2.50	2.50	2.50			
32	20	16	10	6.3			0.56	0.77	1.30	1.83	2.15	2.37			
40	20	25	16	10			0.36	0.49	0.84	1.19	1.40	1.54			
50		40	25	16			0.17	0.25	0.47	0.68	0.81	0.89	1.19	1.53	1.74
65		63	40	25			0.10	0.15	0.28	0.41	0.49	0.54	0.72	0.93	1.06
80		100	63	40			0.06	0.10	0.19	0.28	0.33	0.36	0.49	0.63	0.71
100		160	100	63						0.14	0.17	0.19	0.28	0.37	0.43
125	40	250	160	100						0.09	0.11	0.12	0.18	0.24	0.28
150		360	250	160						0.06	0.07	0.09	0.12	0.17	0.19

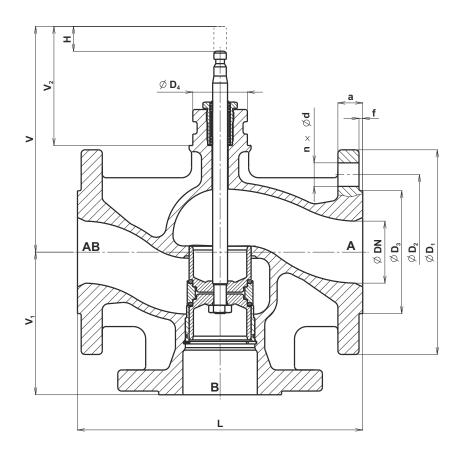


			stroke
is El	Electric actuator SAX 3:	a SAX 31.03 AC 230 V, 3-position control, 700 N	
E	Electric actuator SAX 8	a SAX 81.03 AC/DC 24 V,3-position control, 800 N	20 mm
E	Electric actuator SAX 6	AC/DC 24 V, 3-position control, 010V, 420mA, 0 to 1000 Ohm, 80	N
E	lectric actuator NV23	E AC 230 V,3-position control, 1000 N	
E	Electric actuator NV24	AC/DC 24 V,3-position control , 1000 N	
E	lectric actuator NV24	P-RE AC/DC 24 V, DC (0) 210V, 1000 N	
El	Electric actuator NVC2	P-RE AC/DC 24 V, DC (0) 210V, 1000 N	
E	Electric actuator NVK2	-RE AC/DC 24 V,3-position control , 1000 N	
El	Electric actuator NVK2	IP-RE AC/DC 24 V, DC (0) 210V, 1000 N	
E	electric actuator NVK2	3-RE AC 230 V,3-position control, 1000 N	20 mm
E	Electric actuator NVKC	MP-RE AC/DC 24 V, DC (0) 210V, 1000 N	
E	Electric actuator SV24	-RE AC/DC 24 V, DC (0) 210V, 1500 N	
E	Electric actuator SV23 0	AC 230 V,3-position control, 1500 N	
E	Electric actuator SV24	AC/DC 24 V,3-position control, 1500 N	
El	Electric actuator SVC24	P-RE AC/DC 24 V, DC (0) 210V, 1500 N	
E	Electric actuator EV23 0	AC 230 V,3-position control, 2500 N	
E	Electric actuator EV24	AC/DC 24 V,3-position control, 2500 N	
E	Electric actuator EV24	-RE AC/DC 24 V, DC (0) 210V, 2500 N	40
E	Electric actuator EVC2	F-RE AC/DC 24 V, DC (0) 210V, 2500 N	40 mm
E	Electric actuator RV24	-RE AC/DC 24 V, DC (0) 210V, 4500 N	
E	Electric actuator PTN2	AC 230 V, 3-position control,	
		010V, 420mA, 2000 - 4000 N	20.40
E	Electric actuator PTN2	AC 24 V, 3-position control, 010V, 420mA, 2000 - 4000 N	20 - 40 mm
El	Electric actuator ANT4	AC/DC 24 V (230 V with modul), 2500 N	
	lastria astructor ANTA	3(2)-position control, 010V, 420mA	
E	Electric actuator ANT4	7,	20 10
		3(2)-position control, 010V, 420mA	20 - 40 mm
	Electric actuator ANT4	fail-safe function - indirect	
	LIECTIC actuator ANT4	7.0,502.1. (200.10.11), 2000.1.	
		3(2)-position control, 010V, 420mA fail-safe function - direct	
Г	Tantria antuntor DCI 20		
ation	Electric actuator PSL2 (AS11 AC 230 V, AC/DC 24 V, 2300 N 3-position control, 0(2)-10 V; 0(4)-20 mA	20 - 40 mm
	Electric actuator PSL2 (
	lectific actuator F3L20	3-position control, 0(2)-10 V; 0(4)-20 mA	
F	Electric actuator PSL2 (·	40 mm
	lectific actuator F3L20	3-position control, 0(2)-10 V; 0(4)-20 mA	
F	Electric actuator PSF4 0	AC 230 V, AC/DC 24 V, 1000 N	
	fail-safe function)	3-position control, 0(2)-10 V; 0(4)-20 mA	20 mm
	Flectric actuator PSF40	AC 230 V, AC/DC 24 V, 2000 N	
		, , ,	
			20 - 40 mm
(fa E) (fa	fail-safe function) Electric actuator PSF4(fail-safe function) Electric actuator PSF-N hand wheel)	3-position control, 0(2)-10 V; 0(4)-20 mA AC 230 V, AC/DC 24 V, 2000 N 3-position control, 0(2)-10 V; 0(4)-20 mA	20



Dim	ensior	ns and	l weig	hts fo	r the	type	RV 11	3 M							
				PN 6				PN 16							
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₁	D ₂	D ₃	d	n	а	m	
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	
15	80	55	38	11	4	12	2.6	95	65	46	14	4	14	3.5	
20	90	65	48	11	4	14	3.5	105	75	56	14	4	16	4.6	
25	100	75	58	11	4	14	4.1	115	85	65	14	4	16	5.4	
32	120	90	69	14	4	16	6.3	140	100	76	19	4	18	8.5	
40	130	100	78	14	4	16	7.9	150	110	84	19	4	18	10.5	
50								165	125	99	19	4	20	16.7	
65								185	145	118	19	4	20	23.0	
80								200	160	132	19	8	22	29.5	
100								220	180	156	19	8	24	40.5	
125								250	210	184	19	8	26	58.8	
150								285	240	211	23	8	26	80.7	

				PN 25						PN 6, I	PN 16, P	N 25		
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₄	f	L	V	V ₁	V ₂	н
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
15	95	65	46	14	4	14	3.5	44	2	130	167	65	96	20
20	105	75	56	14	4	16	4.6	44	2	150	167	75	96	20
25	115	85	65	14	4	16	5.4	44	3	160	167	80	96	20
32	140	100	76	19	4	18	8.5	44	3	180	177	90	96	20
40	150	110	84	19	4	19	10.5	44	3	200	187	100	96	20
50	165	125	99	19	4	19	13.0	44	3	230	182	115	96	20
65	185	145	118	19	8	19	18.3	44	3	290	192	145	96	20
80	200	160	132	19	8	19	24.1	44	3	310	212	155	96	20
100	235	190	156	23	8	19	33.1	44	3	350	247	175	116	40
125	270	220	184	28	8	19	46.9	44	3	400	272	200	116	40
150	300	250	211	28	8	20	66.7	44	3	480	297	240	116	40







RV 113 L

Two-way control valves

DN 15 - 40, PN 6 DN 15 - 150, PN 16 DN 15 - 150, PN 25

Technical data									
Series	RV 1:	13 L							
Type of valve	Two-way co	ntrol valve							
Nominal size range	DN 15 t	to 150							
Nominal pressure	DN 15 - 40, PN 6; DN 15 - 150, PN 16	DN 15 - 150, PN 25							
Body material	Grey cast iron EN-JL 1040 Spheroidal cast iron EN-								
Plug material	Stainless steel 1.4027 (1.4028)								
Stem material	Stainless stee	1.4305							
Seat sealing	EPC	DM							
Packing	EPC	DM							
Operating temperature range	+2 to +	150 °C							
Connection	Flanges type B1 (r	aised-faced) V 1092-2 (1/1999)							
Face to face dimensions		5N-EN 558 + A1 (5/2012)							
		. , ,							
Type of plug	V-ported with so	<u> </u>							
Flow characteristic	LDMspline*								
Kvs values	0,63 to 36	,							
Leakage rate	Class IV S1 acc. to ČSN-EN 1	349 (5/2001) (<0.0005 % Kvs)							
Rangeability r	50	:1							

pressures [MPa] acc. to			
Material	PN	Tempera	ture [°C]
	PIN	120	150
Grey cast iron EN-JL 1040	6	0,60	0,54
(EN-GJL-250)	16	1,60	1,44
Spheroidal cast iron EN-JS 1025 (EN-GJS-400-18-LT)	25	2,50	2,43



Kvs values and differential pressures

The value $\Delta p_{\text{\tiny max}}$ is maximum differential pressure when reliable closing and opening is guaranteed. Because of the seat and plug service life, it is recommended so that permanent differential pressure would not exceed 0.4 MPa (Grey cast iron) respective 0.6 Mpa (Spheroidal cast iron).

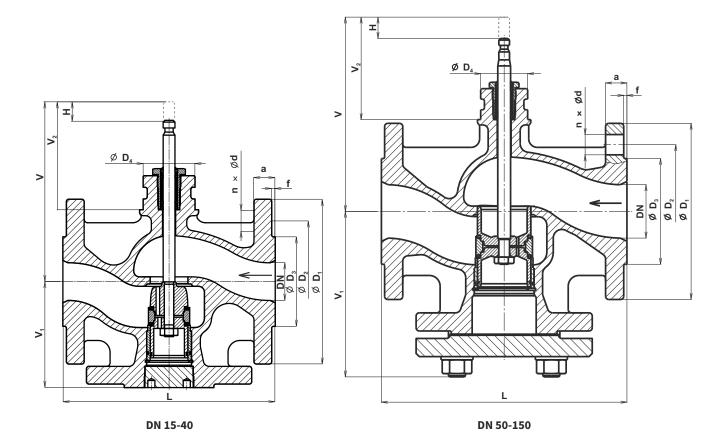
For furth	ner info.	Actua	ting (a	ctuato	or)		see the ta	ble below
actuator		Linea	r force				1000 N	2800 N
catalogu	ie sheets		K	/s [m³/	h]		$\Delta p_{\scriptscriptstyle{ ext{max}}}$	$\Delta p_{_{ m max}}$
DN	H 1 2			3	4	5		
15		4	2.5	1.6	1	0.63	2.50	
20		6.3	4.0	2.5			1.96	
25		10	6.3 4.0			1.25	2.50	
32	20	16 10 6.3	6.3			2.50	2.50	
40	20	25	16	10			2.50	2.50
50		40	25	16			2.50	2.50
65		63	40	25			2.50	2.50
80		100	63	40			2.50	2.50
100		160	100	63				2.50
125	40	250	160	100				2.50
150		360 250 160			2.50			

			stroke
	Electrohydraulic actuator SKD 32.50	AC 230 V, 3-position control, 120 s, 1000 N	
	Electrohydraulic actuator SKD 82.50	AC 24 V, 3-position control, 120 s, 1000 N	
	Electrohydraulic actuator SKD 32.51	AC 230 V, 3-position control, 120 s, fail-safe fct., 1000 N	
Siemens	Electrohydraulic actuator SKD 32.21	AC 230 V, 3-position control, 30 s, fail-safe funct., 1000 N	20 mm
Siciliciis	Electrohydraulic actuator SKD 82.51	AC 24 V, 3-position control, fail-safe function, 1000 N	20 111111
	Electrohydraulic actuator SKD 60	AC 24 V, control 010 V, 420 mA, 0-1000Ω, 1000 N	
	Electrohydraulic actuator SKD 62	AC 24 V, control 010 V, 420 mA, 0-1000Ω, fail-safe fct., 1000 N	
	Electrohydraulic actuator SKD 62UA	AC 24 V, control 010 V, 420 mA, 0-1000Ω, fail-safe fct., 1000 N	
	Electrohydraulic actuator SKB 32.50	AC 230 V, 3-position control, 120 s, 2800 N	
	Electrohydraulic actuator SKB 82.50	AC 24 V, 3-position control, 120 s, 2800 N	
	Electrohydraulic actuator SKB 32.51	AC 230 V, 3-position control, 120 s, fail-safe fct., 2800 N	
Siemens	Electrohydraulic actuator SKB 82.51	AC 24 V, 3-position control, 120 s, fail-safe fct., 2800 N	20 mm
	Electrohydraulic actuator SKB 60	AC 24 V, control 010 V, 420 mA, 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKB 62	AC 24 V, conrol 010 V, 420 mA, fail-safe fct., 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKB 62UA	AC 24 V, control 010 V, 420 mA, fail-safe fct., 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKC 32.50	AC 230 V, 3-position control, 120 s	
	Electrohydraulic actuator SKC 82.50	AC 24 V, 3-position control, 120 s	
	Electrohydraulic actuator SKC 32.51	AC 230 V, 3-position control, 120 s, fail-safe function	
Siemens	Electrohydraulic actuator SKC 82.51	AC 24 V, 3-position control, 120 s, fail-safe function	40 mm
	Electrohydraulic actuator SKC 60	AC 24 V, control 010 V, 420 mA, 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKC 62	AC 24 V, control 010 V, 420 mA, fail-safe function, 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKC 62UA	AC 24 V, control 010 V, 420 mA, fail-safe function, 0-1000Ω, 2800 N	



Dim	ensior	ns and	l weig	hts fo	r the	type	RV 11	3 L						
				PN 6				PN 16						
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₁	D ₂	D ₃	d	n	а	m
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]
15	80	55	38	11	4	12	2.6	95	65	46	14	4	14	3.5
20	90	65	48	11	4	14	3.5	105	75	56	14	4	16	4.6
25	100	75	58	11	4	14	4.1	115	85	65	14	4	16	5.4
32	120	90	69	14	4	16	6.3	140	100	76	19	4	18	8.5
40	130	100	78	14	4	16	7.9	150	110	84	19	4	18	10.5
50								165	125	99	19	4	20	16.7
65								185	145	118	19	4	20	23.0
80								200	160	132	19	8	22	29.5
100								220	180	156	19	8	24	40.5
125								250	210	184	19	8	26	58.8
150								285	240	211	23	8	26	80.7

				PN 25				PN 6, PN 16, PN 25							
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₄	f	L	V	V ₁	V ₂	Н	
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	
15	95	65	46	14	4	14	3.5	44	2	130	167	65	96	20	
20	105	75	56	14	4	16	4.6	44	2	150	167	75	96	20	
25	115	85	65	14	4	16	5.4	44	3	160	167	80	96	20	
32	140	100	76	19	4	18	8.5	44	3	180	177	90	96	20	
40	150	110	84	19	4	19	10.5	44	3	200	187	100	96	20	
50	165	125	99	19	4	19	16.7	44	3	230	182	155	96	20	
65	185	145	118	19	8	19	23.0	44	3	290	192	185	96	20	
80	200	160	132	19	8	19	29.5	44	3	310	212	193	96	20	
100	235	190	156	23	8	19	39.8	44	3	350	247	216	116	40	
125	270	220	184	28	8	19	56.4	44	3	400	272	239	116	40	
150	300	250	211	28	8	20	78.1	44	3	480	297	284	116	40	







RV 113 S

Three-way contol valves

DN 15 - 40, PN 6 DN 15 - 150, PN 16 DN 15 - 150, PN 25

Technical data									
Series	RV 1	13 S							
Type of valve	Three-way cor	ntrol valve							
Nominal size range	DN 15	to 150							
Nominal pressure	DN 15 - 40, PN 6; DN 15 - 150, PN 16	DN 15 - 150, PN 25							
Body material	Grey cast iron EN-JL 1040	Speroidal cast iron EN-JS 1025							
Plug material	Stainless steel	1.4027 (1.4028)							
Stem material	Stailnless steel 1.4305								
Seat sealing	EPDM								
Packing	EPI	MC							
Operating temperature range	+2 to +	150 ℃							
Connection	Flange type B1 (ra								
		N 1092-2 (4/2002)							
Face to face dimensions	Section 1 acc. to Č	SN-EN 558 + A1 (5/2012)							
Type of plug	V-ported with s	oft seat sealing							
Flow characteristic	LDMspline® in straigth v	vay, linear in angle way							
Kvs values	0,63 to 360 m³/h								
Leakage rate in direct way	Class IV S1 acc. to ČSN-EN 1349 (5/2001) (0.9005 % Kvs)								
Leakage rate in angle way	Not guaranteed	d (<2% Kvs)							
Rangeability r	50	:1							

pressures [MPa] dle ČSN	pressures [MPa] dle ČSN EN 1092-2											
Material	PN	Tempera	ture [°C]									
	PIN	120	150									
Grey cast iron EN-JL 1040	6	0,60	0,54									
(EN-GJL-250)	16	1,60	1,44									
Spheroidal cast iron EN-JS 1025	25	2,50	2,43									
(EN-GJS-400-18-LT)												



Kvs values and differential pressures

The value Δp_{max} is maximum differential pressure when reliable closing and opening is guaranteed. Because of the seat and plug service life, it is recommended so that permanent differential pressure would not exceed 0.4 MPa (Grey cast iron) respective 0.6 Mpa (Spheroidal cast iron).

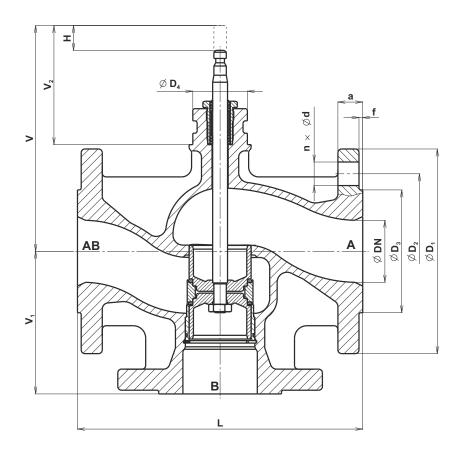
For furth		Actua	ting (a	ctuato	or)		see the ta	ble below
actuator		Linea	r force	•			1000 N	2800 N
catalogu	ie sheets		Kv	/s [m³/	h]		$\Delta p_{\scriptscriptstyle{max}}$	$\Delta p_{\scriptscriptstyle{ ext{max}}}$
DN	Н	1 2 3 4 5				5	MPa	MPa
15		4	2.5	1.6	1	0.63	2.50	
20		6.3	4.0	2.5			1.96	
25		10	6.3	6.3 4.0			1.25	2.50
32	20	16	10	6.3			0.77	2.50
40	20	25	16	10			0.49	1.74
50		40	25	16			0.25	1.02
65		63	40	25			0.15	0.62
80		100	63	40			0.10	0.42
100		160	100	63				0.23
125	40	250	160	100				0.15
150		360	250	160				0.10

Supplie	d types of actuators		
			stroke
	Electrohydraulic actuator SKD 32.50	AC 230 V, 3-position control, 120 s, 1000 N	
	Electrohydraulic actuator SKD 82.50	AC 24 V, 3-position control, 120 s, 1000 N	
	Electrohydraulic actuator SKD 32.51	AC 230 V, 3-position control, 120 s, fail-safe fct., 1000 N	
Siemens	Electrohydraulic actuator SKD 32.21	AC 230 V, 3-position control, 30 s, fail-safe funct., 1000 N	20 mm
Siciliciis	Electrohydraulic actuator SKD 82.51	AC 24 V, 3-position control, fail-safe function, 1000 N	20 111111
	Electrohydraulic actuator SKD 60	AC 24 V, control 010 V, 420 mA, 0-1000Ω, 1000 N	
	Electrohydraulic actuator SKD 62	AC 24 V, control 010 V, 420 mA, 0-1000Ω, fail-safe fct., 1000 N	
	Electrohydraulic actuator SKD 62UA	AC 24 V, control 010 V, 420 mA, 0-1000Ω, fail-safe fct., 1000 N	
	Electrohydraulic actuator SKB 32.50	AC 230 V, 3-position control, 120 s, 2800 N	
	Electrohydraulic actuator SKB 82.50	AC 24 V, 3-position control, 120 s, 2800 N	
	Electrohydraulic actuator SKB 32.51	AC 230 V, 3-position control, 120 s, fail-safe fct., 2800 N	
Siemens	Electrohydraulic actuator SKB 82.51	AC 24 V, 3-position control, 120 s, fail-safe fct., 2800 N	20 mm
	Electrohydraulic actuator SKB 60	AC 24 V, control 010 V, 420 mA, 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKB 62	AC 24 V, conrol 010 V, 420 mA, fail-safe fct., 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKB 62UA	AC 24 V, control 010 V, 420 mA, fail-safe fct., 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKC 32.50	AC 230 V, 3-position control, 120 s	
	Electrohydraulic actuator SKC 82.50	AC 24 V, 3-position control, 120 s	
	Electrohydraulic actuator SKC 32.51	AC 230 V, 3-position control, 120 s, fail-safe function	
Siemens	Electrohydraulic actuator SKC 82.51	AC 24 V, 3-position control, 120 s, fail-safe function	40 mm
[Electrohydraulic actuator SKC 60	AC 24 V, control 010 V, 420 mA, 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKC 62	AC 24 V, control 010 V, 420 mA, fail-safe function, 0-1000Ω, 2800 N	
	Electrohydraulic actuator SKC 62UA	AC 24 V, control 010 V, 420 mA, fail-safe function, 0-1000Ω, 2800 N	



Dim	ensior	ns and	l weig	hts fo	r the	type	RV 11	3 S						
				PN 6				PN 16						
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₁	D ₂	D ₃	d	n	а	m
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]
15	80	55	38	11	4	12	2.6	95	65	46	14	4	14	3.5
20	90	65	48	11	4	14	3.5	105	75	56	14	4	16	4.6
25	100	75	58	11	4	14	4.1	115	85	65	14	4	16	5.4
32	120	90	69	14	4	16	6.3	140	100	76	19	4	18	8.5
40	130	100	78	14	4	16	7.9	150	110	84	19	4	18	10.5
50								165	125	99	19	4	20	16.7
65								185	145	118	19	4	20	23.0
80								200	160	132	19	8	22	29.5
100								220	180	156	19	8	24	40.5
125								250	210	184	19	8	26	58.8
150								285	240	211	23	8	26	80.7

				PN 25				PN 6, PN 16, PN 25							
DN	D ₁	D ₂	D ₃	d	n	а	m	D ₄	f	L	V	V ₁	V ₂	н	
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	
15	95	65	46	14	4	14	3.5	44	2	130	167	65	96	20	
20	105	75	56	14	4	16	4.6	44	2	150	167	75	96	20	
25	115	85	65	14	4	16	5.4	44	3	160	167	80	96	20	
32	140	100	76	19	4	18	8.5	44	3	180	177	90	96	20	
40	150	110	84	19	4	19	10.5	44	3	200	187	100	96	20	
50	165	125	99	19	4	19	13.0	44	3	230	182	115	96	20	
65	185	145	118	19	8	19	18.3	44	3	290	192	145	96	20	
80	200	160	132	19	8	19	24.1	44	3	310	212	155	96	20	
100	235	190	156	23	8	19	33.1	44	3	350	247	175	116	40	
125	270	220	184	28	8	19	46.9	44	3	400	272	200	116	40	
150	300	250	211	28	8	20	66.7	44	3	480	297	240	116	40	





		XX	XXX	X	XX XX	XX	/ XXX	- XXX	(X
Valve	Control valve	RV							
2. Series	Valves made of grey cast iron		113						
3. Type of valve	Two-way control valve			R					
	Three-way control valve			М					
	Two-way control valve for electrohydraulic actuators			L					
	Three-way control valve for electrohydraulic actuators			S					
. Execution	Flanged, two-way				4				
	Flanged, three-way mixing (diverting)				6				
. Body material	Grey cast iron (PN 06, 16)				3				
	Spheroidal cast iron (PN 25)				4				
. Flow characteristic	LDMspline® / linear				3				
'. Kvs	Column No. acc. to Kvs value table				Х				
. Nominal pressure PN	PN 6 (grey cast iron only) DN 15 to 40					06			
	PN 16 (grey cast iron only)					16			
	PN 25 (spheroidal cast iron only)					25			
). Max. temperature °C	150°C						150		
). Nominal size DN	DN 15 to 150							XXX	
. Execution	Normal								
	Silicone free								SI

Order example: **RV113 R 4331 16/150-065**The actuator must be specified separately.





Electric actuators

LDM

ANT40.11

Description

The actuators are designed for regulators with continuous or contact output. They are suitable to actuate two-way and three-way valves series RV 113 and RV 2xx. The actuator consists of cover made of self-extinguishing plastic housing a stepping motor, control unit with SUT technology, signalisation LEDs and no-maintenenance gear made of sintered steel. The connection to its valve is provided by stainless steel columns and yoke made of light metal alloy. Electric connection (max. 2,5 mm2) is provided with the aid of screw clamps. There are three self-breaking openings for cable gands M20x1,5 (2x) and M16x1,5. One cable gland M20x1,5 is a part of standard delivery.

Application

Based on a connection variant (see wiring diagram), the actuator can be used as floating (0...10 V or 4...20 mA), or 2-position (open-closed) or 3-position (open-stop-closed). Manual operating is available with outer handle. The motor is disconnected when the hand crank is folded back. When the handle is positioned back, the actuator resumes into required position (without initialization). If the hand crank remains folded out, the actuator keeps its set position.

Installation position

Upright, vertical, max. horizontal.

SUT Technology

The actuator can be controlled by regulators with continuous (0...10 V and/or 4...20 mA) or contact (2-position or 3-position) output. The actuator feeding is optional. The running speed and output characteristic is also optional.

Features

- electronic switch off based on the running force registered by stops inside appliance or valve.
- automatic adapting to the valve stroke
- code switch for characteristic and running time selection
- hand crank for manual operating with swithing the motor off as a start for new initiation
- possibility of direction change of control signal (feeding voltage at terminal 2a or 2b)

Technical data	
Туре	ANT40.11
Suitable for valves	RV 113 R, M
Execution	Electric actuator with SUT technology
Voltage	24 V AC ± 20%, 50 - 60 Hz; 24 V DC ± 15%; 230 V AC ± 15%
Frequency	50 Hz
Power consumption	18 VA
Control	0 - 10 V, 4 - 20 mA, 3-bod., 2-bod.
Open-close running time	Adjustable 2, 4, 6 s.mm ⁻¹
Nominal force	2500 N
Travel	20 and 40 mm
Enclosure	IP 66
Process medium max. temp.	150°C
Ambient temperature range	-10 and 55°C
Ambient humidity range	< 95 % of relative humidity
Weight	4,5 kg



Accessories

0313529 001 0372332 001	Split range unit to set sequences Module, plug-in type, for 230 V \pm 15% voltage supply and 3-point activation, additional power 2 VA
0372333 001	2 auxiliary changeover switches, continuously adjustable, additional load 5(2) A, 12 - 250 V, 3(1) A, 12 - 250 V AC ¹⁾
0372333 002	2 auxiliary changeover contacts with gold-plated contacts for low currents from 1 mA, max. 30 V, 3(1) A, 12 - 250 V AC ¹⁾
0372334 001	Potentiometer 2000 Ω, 1 W, 24 V ¹⁾
0372334 002	Potentiometer 130 Ω , 1 W, 24 V $^{\scriptscriptstyle 1)}$
0372334 006	Potentiometer 1000Ω , $1 W$, $24 V^{1}$
0386263 001	Screwed cable gland M16 x 1,5
0386263 002	Screwed cable gland M20 x 1,5 (1 piece of cable gland is standard part of actuator delivery)

¹⁾ one option of accessory can be used only

Operation

Initialisation and feedback signal

When used as a continuous drive, the device initialises itself automatically. As soon as voltage is applied to the drive for the first time, it moves to the lower limit stop on the valve, thus enabling automatic connection with the valve spindle. Then it moves to the upper limit stop and the value is recorded and saved with the help of a path measurement system. The control signal and the feedback signal are adjusted to this effective stroke. There is no re-initialisation if the voltage is interrupted or if the voltage supply is removed. The values remain saved. To re-initialise, the drive must be connected to the voltage. To trigger an initialisation, fold the hand crank out and back in again twice within

4 seconds. Both the LEDs will then flash red.
During initialisation, the feedback signal is inactive, or it corresponds to a value of "0". Initialisation uses the shortest run time. The reinitialisation is only valid once the entire procedure has been completed. Folding the

hand crank out again will interrupt the procedure. If the valve drive detects a blockage, it will report this by setting the feedback signal to 0 V after approx. 90 s. However, the drive will try to overcome the blockage during this time. If it is possible to overcome the blockage, the normal control function is activated again and the feedback signal is resumed.

No initialisation is performed with a 2-position or 3-position control. The feedback signal is inactive.

Connection as a 2-point valve drive (24 V)

This activation (OPEN/CLOSED) can take place via two cables. The voltage is applied to terminals 1 and 2a. Applying the voltage (24 V) to terminal 2b opens the valve's control passage. After this voltage has been switched off, the drive moves to the opposite end position and closes the valve. The electronic motor switch-off responds in the end positions (valve limit stop, or when maximum stroke is reached) or in case of overload (no limit switches).

The coding switch can be used to set the run times. The characteristic curve cannot be selected in this case (resulting in the characteristic curve for the valve). Terminals 3i, 3u and 44 must not be connected.

Connection as a 3-point valve drive (24V)

Applying voltage to terminal 2a (or 2b) makes it possible to move the valve to any desired position. If voltage is applied to terminals 1 and 2b, the valve shaft moves out and opens the valve. It moves in and closes the valve when the electrical circuit is closed over terminals 1 and 2a.

In the end positions (at the valve stop, or when the maximum stroke is reached) or in case of an overload, the electronic motor switch-off responds (no limit switches). The direction of the stroke can be changed by transposing the connections.

The coding switch is used to set the run times. In this case, the characteristic curve cannot be selected (resulting in the characteristic curve for the valve). Terminals 3i, 3u and 44 must not be connected.

Connection as a 2-point/3-point or continuous activation of valve drive with 230 V (accessory 0372332)

The accessory module is plugged on in the connection area and is then connected for 3-position mode. If this accessory is used, only control in 3-position mode is available. The coding switch on the baseboard can be used to select the run times. The characteristic curve cannot be selected; the characteristic curve for the valve is applicable.

The module has a built-in switch which is automatically moved into the correct position when the module is installed. On this drive (which has no spring return action) the switching lever is in the lower position.

The accessory module is not suitable for 2-position activation.

Connection as continuous control (0...10 V and/or 4...20 mA) - (24V)

The built-in positioner controls the drive depending on the controller output signal y.

The control signal used is a voltage signal $(0...10 \, \text{V}-)$ at terminal 3u, or a current signal at terminal 3i. If a control signal is present at both terminals $(3u \, (0...10 \, \text{V})$ and 3i $(4...20 \, \text{mA}))$ simultaneously, the input with the higher value takes priority.

Mode of action 1 (mains voltage to internal connection 2a):

as the output signal increases, the valve shaft moves out and opens the valve (control passage).

Mode of action 2 (mains voltage to internal connection 2b):

as the output signal increases, the valve shaft moves in and closes the valve (control passage).

The starting point and the control span are fixed. To set partial ranges (and only for voltage input 3u), a split range unit is available as an accessory (see the split range unit function); this unit is intended for installation in the drive.

After the voltage supply is applied and after initialisation, the drive moves to each valve stroke between 0% and 100%, depending on the control signal. The electronics and the path measurement system ensure that no stroke is lost, and the drive does not require reinitialisation at intervals. When the end positions are reached, the position is checked, corrected as necessary and stored again. This ensures parallel running of several drives of the same SUT type. Feedback signal y0 = 0...10 V corresponds to the effective valve stroke of 0 to 100%

If the 0...10 V control signal is interrupted in direction of action 1, the spindle retracts completely and the valve is closed. So that the valve can be opened (direction of action 1), a voltage of 10 V must be connected between terminals 1 and 3u, or it is necessary to switch over to direction of action 2.

 $The coding \, switch \, can \, be \, used \, to \, set \, the \, characteristic for \, the \, valve.$



Signal LED display

Both LEDs flashing red: initialisation procedure

Upper LED lit red: upper limit stop or "CLOSED" position reached

Lower LED lit red: lower limit stop or "OPEN" position reached

Upper LED flashing green: drive running, moving towards "CLOSED" position

Upper LED lit green: drive stationary, last direction of running "CLOSED"

Lower LED flashing green: drive running, moving towards "OPEN" position

Lower LED flashing green: drive stationary, last direction of running "OPEN"

Both LEDs are lit green: waiting time after switching on, or after emergency function

No LED lit: no voltage supply (terminal 2a or 2b)

Both LEDs are flashing red and green: drive is in manual mode

Accessories application

Split range unit

This accessory can be built into the drive or can be accommodated externally in an electrical distribution box. The starting point Uo and the control span ΔU can be set with the help of a potentiometer. This makes it possible to operate several regulating units in sequence or in a cascade with the control signal from the controller. The input signal (partial range) is converted into an output signal of 0...10 V.

Auxiliary changeover switch

Auxiliary changeover switch double 0372333 001

- Switching capacity max. 250 V~, min. current 250 mA at 12 V (or 20 mA at 20 V)
- Switching capacity max. 12...30 V=, max. current 100 mA

Auxiliary changeover switch double gold 0372333 002

- Switching capacity max. 250 V~, min. current 1 mA at 5 V
- Switching capacity max. 0.1...30 V=, current 1...100 mA

Even if used only once above 10 mA or up to 50 V, the gold coating will be destroyed. The switch can then be used only for higher switching outputs.

Engineering and installation notes

Penetration of condensate or dripping water, etc. along the valve spindle into the drive should be avoided.

The valve is plugged directly onto the drive and is fixed with screws (no further settings are needed). The drive is automatically connected to the valve spindle. When the device is delivered, the drive spindle is in the middle position.

The housing contains three breakthrough-type cable leadthroughs which are broken open automatically when the cable leadthrough is screwed in. The stepping motor/ electronics concept guarantees parallel running of several valve drives of the same type. The cross-section of the connecting cable should be selected according to the line length and the number of drives. With five drives connected in parallel and a line length of 50 m, we recommend using a cable cross-section of 1.5 mm² (power consumption of the drive \times 5). The drive can be assembled with a maximum of one 230 V module, one additional accessory component (auxiliary switch or potentiometer) and the split range unit.

Warnings

If the temperature of the medium in the valve is high, the drive columns and the shaft may also reach high temperatures. It is necessary to ensure that the maximum ambient temperature be max. 55°C during operation. If the temperature exceeds this limit, it is recommended to insulate the valve (eg. IKA insulation, see catalogue sheet 01-09.6).

If a failure of the final control element could cause damage, additional protective precautions must be taken.

CE - Conformity

Directive EMC 2014/30/ES

EN 61000-6-2 *) EN 61000-6-4 Low Voltage Directive 2014/35/ES

EN 60730 1 EN 60730-2-14 Over-voltage ca

Over-voltage category III
Degree of pollution III

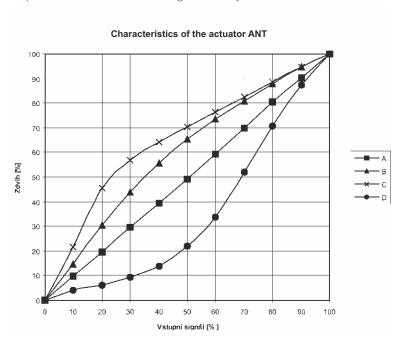
^{*)} HF immunity, limitation of feedback signal between 80 MHz a 1000 Mhz criterion B, otherwise criterion A

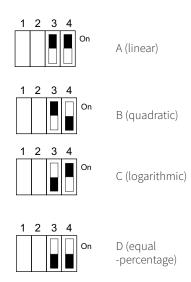


Switch coding

Actuator characteristic (switches 3 and 4)

- optional for actuators with floating control only





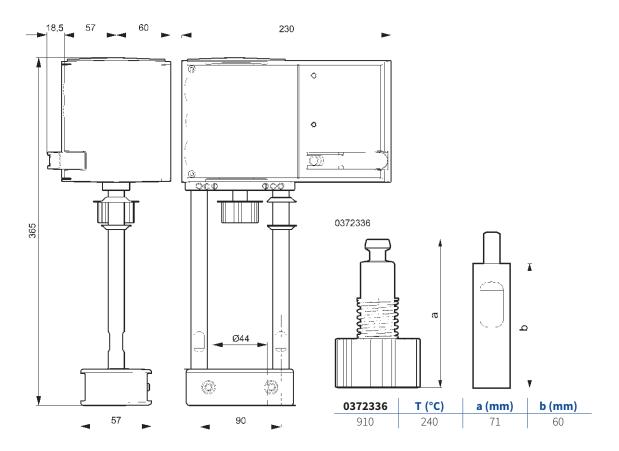
Run time (switches 1 and 2) - optional for all types of control of the actuator

Run time per mm	Switch coding	Run time for stroke 20 mm	Run time for stroke 40 mm
2 s / mm	1 2 3 4 On	40 s ± 1	80 s ± 2
4 s / mm	1 2 3 4	80 s ± 2	160 s ± 4
6 s / mm	1 2 3 4 on 1 2 3 4 on on	120 s ± 4	240 s ± 8

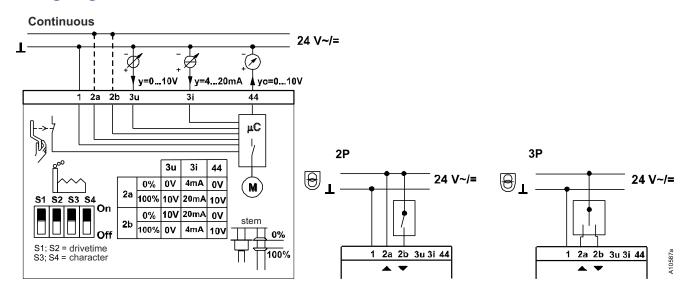
Note: Data in bold mean factory settings



Dimensions of actuator and a mid piece for higher temperatures

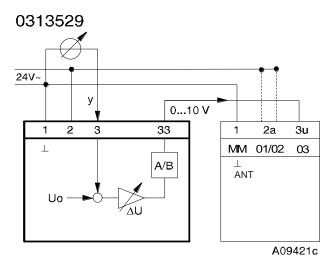


Wiring diagram of actuators

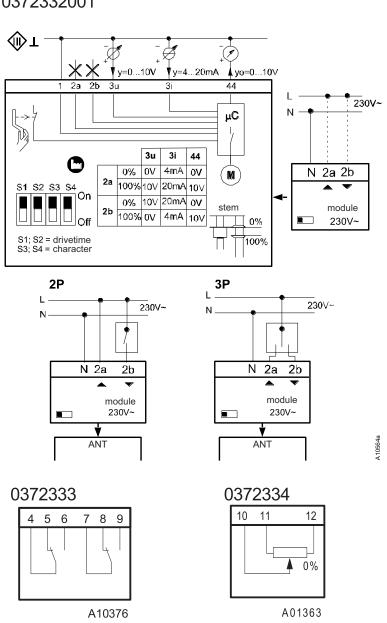




Wiring diagram of accessories



0372332001







Electric actuators

LDM

ANT40.11S ANT40.11R

Description

The actuator is designed for regulators with continuous or contact output. They are suitable for actuating two-way or three way valves series RV 113 and RV 2xx. The actuator is equipped with a spring ensuring the actuator runs into its defined end position in case of power supply failure or when the sensor of limit value is activated. The actuator consists of a cover made of self-extinguishing plastic housing stepping motor, control unit with SUT technology, signalisation LEDs and no-maintenance gear made of sintered steel and spring roll. The connection to its valve is provided by stainless steel columns and yoke made of light metal alloy. Electric connection (max. 2,5 mm2) is provided with the aid of screw clamps. There are three self-breaking openings for cable gands M20x1,5 (2x) and M16x1,5. One cable gland M20x1,5 is a part of standard delivery.

Application

Based on a connection variant (see wiring diagram), the actuator can be used as floating (0...10 V or 4...20 mA), or 2-position (open-closed) or 3-position (open-stop-closed). Manual operating is with outer hand crank. The motor is disconnected when the hand crank is folded out. When the hand crank is folded back, the actuator resumes into required position (without initialization). If the hand crank remains folded out, the actuator keeps its set position.

Installation position

Upright, vertical, max. horizontal.

SUT Technology

The actuator can be controlled by regulators with continuous $(0...10 \, \text{V} \, \text{and/or} \, 4...20 \, \text{mA})$ or contact $(2\text{-position} \, \text{or} \, 3\text{-position})$ output. The actuator feeding is optional. The running speed and output characteristic is also optional.

Features

- electronic switch off based on the running force registered by stops inside apliance or valve
- automatic adapting to the valve stroke
- code switch for characteristic and running time selection
- hand crank for manual operating with swithing the motor off as a start for new initiation
- possibility of direction change of control signal (feeding voltage at terminal 2a or 2b)

Direct and indirect function of actuator

Direct function ensures that actuator stem extends (the valve opens) upon power supply failure. Indirect function ensures that actuator stem retracts (the valve closes) upon power supply failure.

Technical data			
Туре	ANT40.11S ANT40.11R		
Specification code	RV 113 R, M		
Execution	Electric actuator with spring return action and SUT technology		
Voltage	24 V AC ± 20%, 50 - 60 Hz; 24 V DC ± 15%; 230 V AC ± 15%		
Frequency	50 Hz		
Powe consumption	in operation mode 20 VA, v klidu 7 VA		
Control	0-10 V, 4-20 mA,		
	3-position, 2-position		
Open-close running time	Adjustable 2, 4, 6 s.mm ⁻¹		
Running time for fail-safe function	Acc. to stroke 15 - 30 s		
Fail-safe function	indirect (NC) Direct (NO)		
Nominal force	2000 N		
Stroke	20 and 40 mm		
Enclosure	IP 66		
Process medium max. temperature	150 °C		
Ambient temperature range	-10 to 55 °C		
Ambient humidity range	< 95 % of relative humidity		
Weight	6,1 kg		



Accessories

0313529 001 0372332 001	Split range unit to set sequences Module, plug-in type, for 230 V ± 15% voltage supply and 3-point activation, additional power 2 VA
0372333 001	2 auxiliary changeover switches, continuously adjustable, additional load 5(2) A, 12 - 250 V, 3(1) A, 12 - 250 V AC ¹⁾
0372333 002	2 auxiliary changeover contacts with gold-plated contacts for low currents from 1 mA, max. 30 V, 3(1) A, 12 - 250 V AC ¹⁾
0372334 001	Potentiometer 2000 Ω , 1 W, 24 V $^{\scriptscriptstyle 1)}$
0372334 002	Potentiometer 130 Ω , 1 W, 24 V $^{\scriptscriptstyle 1)}$
0372334 006	Potentiometer 1000 Ω , 1 W, 24 V 11
0386263 001	Screwed cable gland M16 x 1,5
0386263 002	Screwed cable gland M20 x 1,5 (1 piece of cable gland is standard part of actuator delivery)

¹⁾ one option of accessory can be used only

Operation

After a new start, or after a start following activation of the reset (terminal 21), up to 45 s of waiting time will pass before the drive is available again. Depending on the type of connection (see the wiring dia-gram), the device can be used as a continuous-action drive (0...10 V and/or 4...20 mA), a 2-point drive (open-closed) or a 3-position drive (open-stop-closed).

Initialisation and feedback signal

The drive initialises itself automatically, whether it is used in continuous action, 2-position or 3-position mode. As soon as voltage is applied to the drive for the first time and the waiting period has elapsed, the drive moves to the lower limit stop on the valve, thus enabling automatic connection with the valve spindle. Then it moves to the upper limit stop, and the value is recorded and saved with the help of a path measurement system. The control signal and the feedback signal are adjusted to this effective stroke. After an interruption to the voltage or a spring return action, no re-initialisation is performed and the values are saved.

To re-initialise, the drive must be connected to the voltage. To trigger an initialisation, fold the hand crank out and back in again twice within 4 seconds. Both the LEDs will then flash red.

During initialisation, the feedback signal is inactive, or it corresponds to a value of "0". Initialisation uses the shortest run time. The reinitialisation is only valid once the entire procedure has been completed. Folding the hand crank out again will interrupt the procedure.

If the valve drive detects a blockage, it will report this by setting the feedback signal to 0 V after approx. 90 s. However, the drive will try to overcome the blockage during this time. If it is possible to overcome the blockage, the normal control function is activated again and the feedback signal is resumed.

Spring return

If the voltage supply fails or is switched off, or if a monitoring contact responds, the brushless DC mo-tor releases the gear and the drive is moved into the respective end position (depending on the design version) by the pre-tensioned spring. As this happens, the control function of the drive is disabled for 45 s (both LEDs flash green) so that the end position can be reached in every case. The reset speed is controlled with the help of the motor so that there are no pressure surges in the line. The brushless DC motor has three functions: as a magnet to hold the position, as a brake (by acting as a generator) and as a motor for the control function. After a spring return function, the drive does not reinitialise itself.

Connection as a 2-position valve drive (24 V)

This activation (OPEN/CLOSED) can take place via two cables. The voltage is applied to terminals 12a and 21. Applying the voltage (24 V) to terminal 2b causes the coupling rod to extend and opens the valve. After this voltage has been switched off, the drive moves to the opposite end position and closes the valve. The electronic motor switch-off responds in the end positions (valve limit stop, or when maximum stroke is reached) or in case of overload (no limit switches).

The coding switch can be used to set the run times. The characteristic curve cannot be selected in this case (resulting in the characteristic curve for the valve). The feedback signal is active as long as the initialisation is performed and there is voltage present at terminal 21. Terminals 3i, 3u and 44 must not be connected.

Connection as a 3-position valve drive (24 V)

Applying voltage to terminal 2a (or 2b) makes it possible to move the valve to any desired position. If voltage is applied to terminals 1 and 2b, the valve shaft moves out and opens the valve. It moves in and closes the valve when the electrical circuit is closed over terminals 1 and 2a.

In the end positions (at the valve stop, or when the maximum stroke is reached) or in case of an overload, the electronic motor switch-off responds (no limit switches). The direction of the stroke can be changed by transposing the connections.

The coding switch is used to set the run times. In this case, the characteristic curve cannot be selected (resulting in the characteristic curve for the valve). The feedback signal is active as long as the initialisation is performed and there is voltage present at terminal 21. Terminals 3i, 3u must not be connected

Connection as a 3-position valve drive with 230 V

The accessory module is plugged on in the connection area and is then connected for 3-position mode. If this accessory is used, only control in 3-position mode is available. The coding switch on the baseboard can be used to select the run times. The characteristic curve cannot be selected; the characteristic curve for the valve is applicable.

The module has a built-in switch which is automatically moved into the correct position when the module is installed. With this application, the switching lever is in the upper position.

The accessory module is not suitable for 2-position activation.

Connection to a control voltage (0...10 V and/or 4...20 mA)

The built-in positioner controls the drive depending on the controller output signal y.

The control signal used is a voltage signal $(0...10\,V-)$ at terminal 3u, or a current signal at terminal 3i.



If a control signal is present at both terminals (3u (0...10 V) and 3i (4...20 mA) simultaneously, the input with the higher value takes priority.

Mode of action 1 (mains voltage to internal connection 2a): as the output signal increases, the valve shaft moves out and opens the valve (control passage).

Mode of action 2 (mains voltage to internal connection 2b): as the output signal increases, the valve shaft moves in and closes the valve (control passage).

The starting point and the control span are fixed. To set partial ranges (and only for voltage input 3u), a split range unit is available as an accessory (see the split range unit function); this unit is intended for installation in the drive.

After the voltage supply is applied and after initialisation, the drive moves to each valve stroke between 0% and 100%, depending on the control signal.

The electronics and the path measurement system ensure that no stroke is lost, and the drive does not require re-initialisation at intervals. When the end positions are reached, the position is checked, corrected as necessary and stored again. This ensures parallel running of several drives of the same type. Feedback signal $y0 = 0...10 \, \text{V}$ corresponds to the effective valve stroke of 0 to 100%.

If the control signal $0...10\,\mathrm{V}$ is interrupted in mode of action 1, the spindle moves in completely and the valve is closed. So that the valve can be opened (direction of action 1), a voltage of 10 V must be connected between terminals 1 and 3u, or it is necessary to switch over to direction of action 2.

The coding switch can be used to set the characteristic curve for the valve: linear, equal percentage or quadratic. This characteristic curve can only be generated if the drive is used as a continuous drive. Additional switches can be used to select the run times (applicable for 2-position, 3-position or continuous function).

Signal LED display

Both LEDs flashing red: initialisation procedure

Upper LED lit red: upper limit stop or "CLOSED" position reached

Lower LED lit red: lower limit stop or "OPEN" position reached

Upper LED flashing green: drive running, moving towards "CLOSED" position

Upper LED lit green: drive stationary, last direction of running "CLOSED"

Lower LED flashing green: drive running, moving towards "OPEN" position

Lower LED flashing green: drive stationary, last direction of running "OPEN"

Both LEDs are lit green: waiting time after switching on, or after emergency function

No LED lit: no voltage supply (terminal 2a or 2b)

Both LEDs are flashing red and green: drive is in manual mode

Accesories application

Split range unit

This accessory can be built into the drive or can be accommodated externally in an electrical distribution box. The starting point Uo and the control span ΔU can be set with the help of a potentiometer. This makes it possible to operate several regulating units in sequence or in a cascade with the control signal from the controller. The input signal (partial range) is converted into an output signal of 0...10 V.

Auxiliary changeover switch

Auxiliary changeover switch double 0372333 001

- Switching capacity max. 250 V~, min. current 250 mA at 12 V (or 20 mA at 20 V)
- Switching capacity max. 12...30 V=, max. current 100 mA

Auxiliary changeover switch double gold 0372333 002

- Switching capacity max. 250 V~, min. current 1 mA at 5 V
- Switching capacity max. 0.1...30 V=, current 1...100 mA

Even if used only once above $10\,\mathrm{mA}$ or up to $50\,\mathrm{V}$, the gold coating will be destroyed. The switch can then be used only for higher switching outputs.

Engineering and installation notes

Penetration of condensate or dripping water, etc. along the valve spindle into the drive should be avoided.

The valve is plugged directly onto the drive and is fixed with screws (no further settings are needed). The drive is automatically connected to the valve spindle. When the device is delivered, the drive spindle is in the middle position.

The housing contains three breakthrough-type cable leadthroughs which are broken open automatically when the cable leadthrough is screwed in. The stepping motor/ electronics concept guarantees parallel running of several valve drives of the same type. The cross-section of the connecting cable should be selected according to the line length and the number of drives. With five drives connected in parallel and a line length of 50 m, we recommend using a cable cross-section of 1.5 mm² (power consumption of the drive \times 5). The drive can be assembled with a maximum of one 230 V module, one additional accessory component (auxiliary switch or potentiometer) and the split range unit.

Warnings

If the temperature of the medium in the valve is high, the drive columns and the shaft may also reach high temperatures. It is necessary to ensure that the maximum ambient temperature be max.55°C during operation. If the temperature exceeds this limit, it is recommended to insulate the valve (e.g. IKA insulation, see catalogue sheet 01-09.6).

If a failure of the final control element could cause damage, additional protective precautions must be taken.



CE - Conformity

Directive EMC 2014/30/ES

Low Voltage Directive 2014/35/ES EN 60730 1

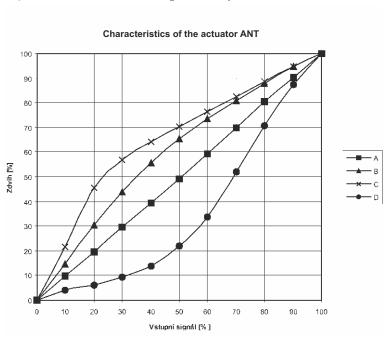
EN 61000-6-2 *) EN 61000-6-4

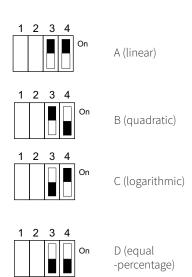
EN 60730-2-14 Over-voltage category III Degree of pollution III

Switch coding

Actuator characteristic (switches 3 and 4)

- optional for actuators with floating control only





Run time (switches 1 and 2)

- optional for all types of control of the actuator

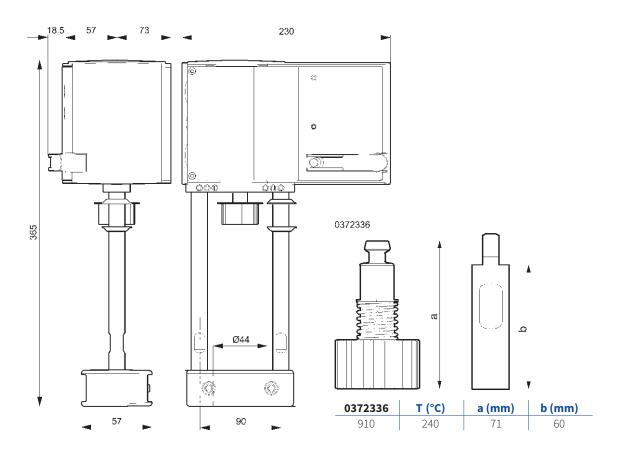
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6 s / mm	1 2 3 4 on 1 2 3 4 on	120 s ± 4	240 s ± 8

Note: Data in bold mean factory settings

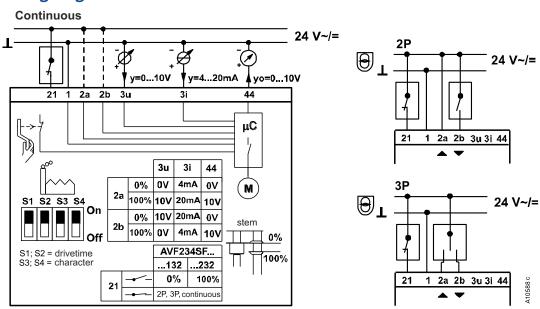
^{*)} HF immunity, limitation of feedback signal between 80 MHz a 1000 Mhz criterion B, otherwise criterion A



Dimensions of actuator and a mid piece for higher temperatures

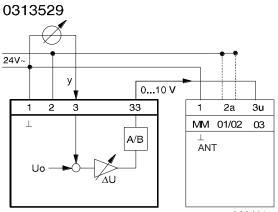


Wiring diagram of actuators

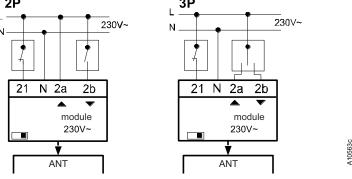


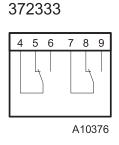


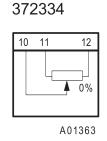
Wiring diagram of accessories



A09421c 0372332001 **⊕**⊥⊸ y=0...10V ▼y=4...20mA **å** yo=0...10∨ 2a 2b 3u 3i 44 μС 3i 44 3u 0% 0V 4mA 0٧ N 2a 2b M) S1 S2 S3 S4 2a 100% 10V 20mA 10V 0% 10V 20mA 0٧ module spindel 100% 0V 4mA 10V 230V~ S1; S2 = drivetime S3; S4 = character AVF234SF. 100% .132 .232 0% 100% 2P, 3P, spojité 2P 3P 230V~











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